

### Features

- 6 Bit Digital Phase Shifter
- 360° Coverage with LSB = 5.6°
- Parallel Control
- Low DC Power Consumption
- Minimal Attenuation Variation over Phase Shift Range
- Bidirectional RF Input/Output
- EAR99
- Bare Die
- RoHS\* Compliant

### Applications

- Cellular Infrastructure
- Phase Array Radars
- Frequency Upconverters
- Test Instruments
- General Purpose

### Description

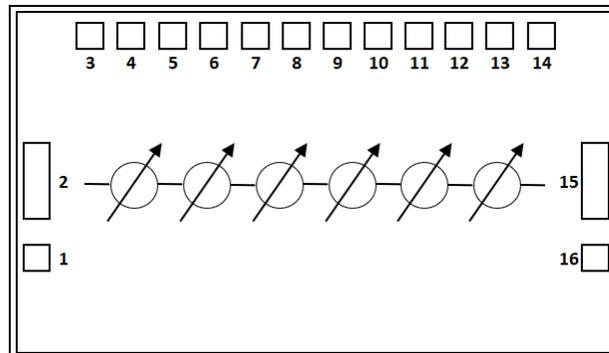
The MAPS-010166-DIE is a GaAs pHEMT 6-bit X-band digital phase shifter. Step size is 5.6° providing phase shift from 0° to 360° in 5.6° steps. This design has been optimized to minimize variation in attenuation over the phase shift range.

The MAPS-010166-DIE is ideally suited for use where high phase accuracy with minimum loss variation over the phase shift range are required. Typical applications include communications antennas and phased array radars. The die size is 2.44 x 1.34 x 0.1 mm.

### Ordering Information

Part Number	Package
MAPS-010166-DIE	Bare Die

### Functional Schematic



### Pad Configuration<sup>1</sup>

Pad #	Name	Function
1, 16	GND	Ground
2	RF <sub>IN</sub>	RF Input
3	A1	5.6° Control
4, 6	N/C	No Connect
5	A2	11.2° Control
7	A3	22.5° Control
8	B3	22.5° Control
9	A4	45° Control
10	B4	45° Control
11	A5	90° Control
12	B5	90° Control
13	A6	180° Control
14	B6	180° Control
15	RF <sub>OUT</sub>	RF Output

1. The backside of the die must be connected to RF, DC, and thermal ground.

\* Restrictions on Hazardous Substances, compliant to current RoHS EU directive.

## Electrical Specifications:

Freq. = 8 - 12 GHz,  $T_A = 25^\circ\text{C}$ ,  $Z_0 = 50 \Omega$ ,  $P_{IN} = 0 \text{ dBm}$ ,  $V_L = -5 \text{ V}$  &  $V_H = 0 \text{ V}$

Parameter	Test Conditions	Units	Min. 8 GHz / 12 GHz	Typ.	Max. 8 GHz / 12 GHz
Insertion Loss (Any Phase State)	Any Phase State	dB	—	5.0	7.0 / 8.75
Attenuation Variation	Across All Phase States	dB	—	$\pm 1.4$	1.9 / 3.2
RMS Attenuation Error	All Values Relative to Insertion Loss at Reference Phase	dB	—	0.7	—
RMS Phase Error <sup>2</sup>	All Values Relative to Reference Phase	Deg.	—	3.0	—
Phase Accuracy Relative to Reference Loss State	5.6 Degree Bit	Deg.	4.5 / 4.25	—	6.5 / 7.25
	11.2 Degree Bit		8.5 / 6.5	—	10.5 / 9.5
	22.5 Degree Bit		22 / 23	—	26 / 27
	45 Degree Bit		44 / 39.5	—	49 / 44.5
	90 Degree Bit		89.5 / 90.5	—	95 / 96
	180 Degree Bit		176 / 179	—	183 / 186
	Sum of All Bits		-4.5 / -0.5	—	3.5 / 7.5
VSWR	RF IN / RF OUT	Ratio	—	1.8:1	—
1 dB Compression	Reference State	dBm	—	27	—
Input IP3	Two-tone inputs up to +5 dBm	dBm	—	45	—
$T_{RISE}$ , $T_{FALL}$	10% to 90% RF, 90% to 10% RF	ns	—	50	—

2. RMS is calculated across all 64 amplitude or phase states relative to the amplitude or phase in the  $0^\circ$  phase state at a given frequency.

$$\delta\text{phase\_RMS} = \sqrt{\frac{1}{n} \sum_{m=1}^n \delta^2\text{phase} - \left(\frac{1}{n} \sum_{m=1}^n \delta\text{phase}\right)^2}$$

## Truth Table<sup>3</sup> (Major BITS)

A1	B2	A2	B3	A3	B3	A4	B4	A5	B5	A6	B6	Phase Shift
$V_L$	X	$V_L$	X	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	Reference Phase
$V_H$	X	$V_L$	X	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	$5.6^\circ$
$V_L$	X	$V_H$	X	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	$11.2^\circ$
$V_L$	X	$V_L$	X	$V_H$	$V_L$	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	$22.5^\circ$
$V_L$	X	$V_L$	X	$V_L$	$V_H$	$V_H$	$V_L$	$V_L$	$V_H$	$V_L$	$V_H$	$45^\circ$
$V_L$	X	$V_L$	X	$V_L$	$V_H$	$V_L$	$V_H$	$V_H$	$V_L$	$V_L$	$V_H$	$90^\circ$
$V_L$	X	$V_L$	X	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	$V_H$	$V_L$	$180^\circ$
$V_H$	X	$V_H$	X	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$V_H$	$V_L$	$354.4^\circ$

3.  $V_L = -5 \text{ V}$ ,  $V_H = 0 \text{ V}$ .

### Maximum Operating Conditions

Parameter	Maximum
Input Power	27 dBm
Input Voltage	0 to -5 V
Operating Temperature	-40°C to +85°C

### Absolute Maximum Ratings<sup>4,5</sup>

Parameter	Absolute Maximum
Input Power	29 dBm
Operating Temperature	-40°C to +85°C
Storage Temperature	-65°C to +150°C

- 4. Exceeding any one or combination of these limits may cause permanent damage to this device.
- 5. MACOM does not recommend sustained operation near these survivability limits.

### Handling Procedures

Please observe the following precautions to avoid damage:

### Static Sensitivity

These electronic devices are sensitive to electrostatic discharge (ESD) and can be damaged by static electricity. Proper ESD control techniques should be used when handling these 200 V HBM, Class 0B devices.

### Mounting and Bonding Information

The DIE should be directly attached to the RF/DC ground plane; either with solder (AuSn) or a thin application of conductive epoxy. Avoid overflows.

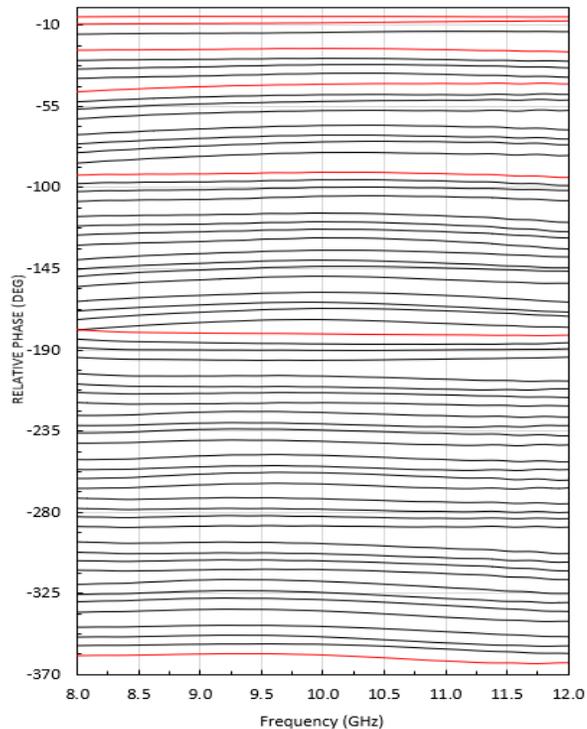
Any connecting microstrip (50 Ω Transmission Line) substrate should be brought as close as possible to the die in order to minimize bond wire inductance. A typical spacing between die and microstrip substrate should be kept between 75 - 125 μm for best RF behavior.

Two Bond-Wires are recommended on pad 2, and 15 (1mil diameter each). All bonds should be kept as short as possible.

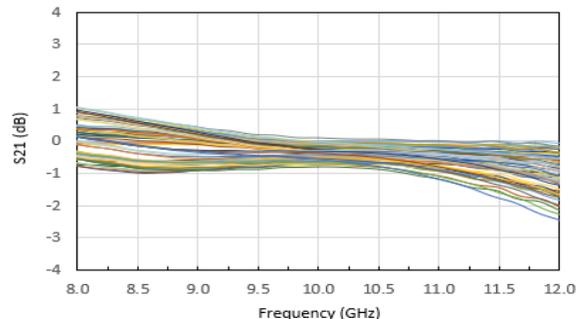
Use minimum ultrasonic energy for reliable wire bonds.

## Typical Performance Curves

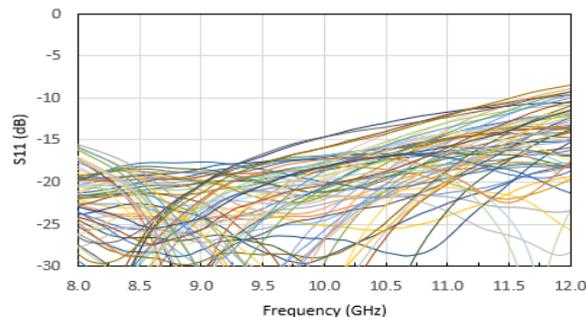
**Normalized Phase Shift vs. Frequency**



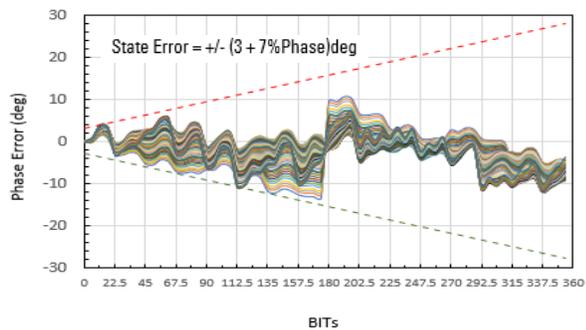
**Normalized Attenuation Variation**



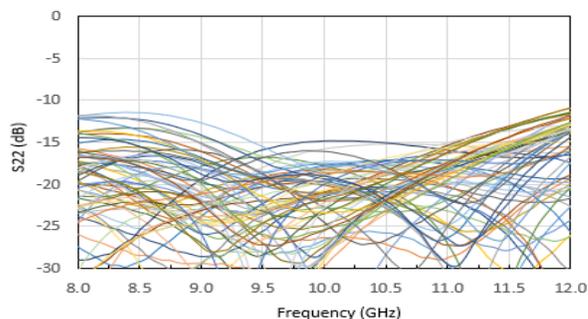
**Input Return Loss (All States)**



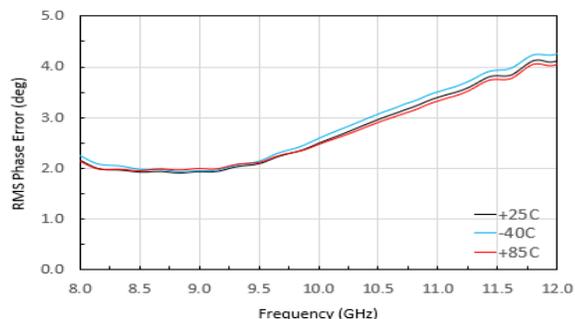
**Phase Error vs. State (All States)**



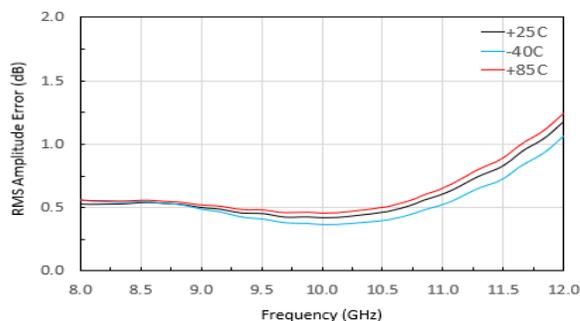
**Output Return Loss (All States)**



**RMS Phase Error vs. Temp**

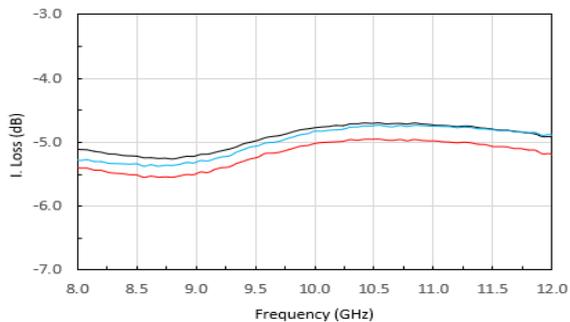


**RMS Amplitude Error vs. Temp**

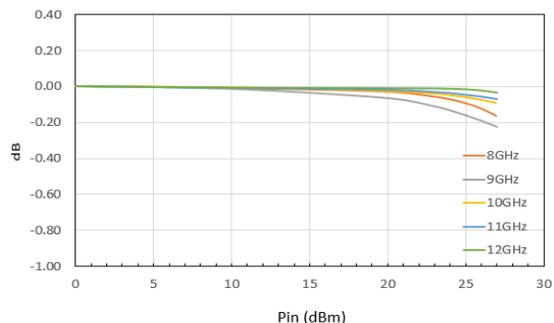


## Typical Performance Curves

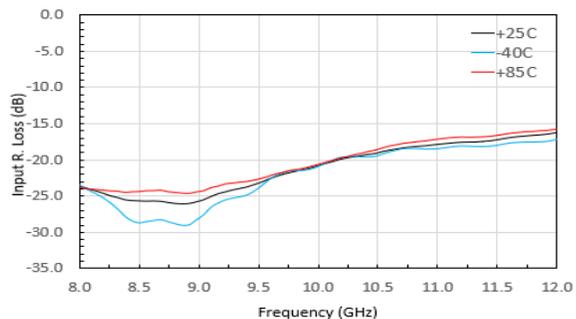
**Insertion Loss vs. Temp**



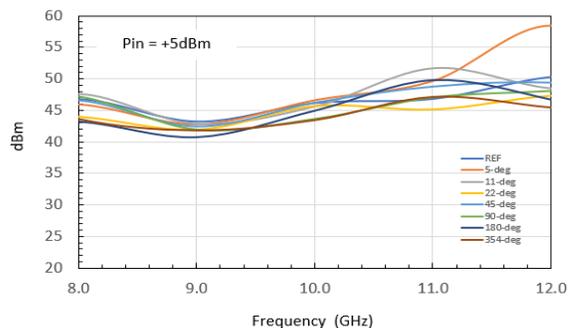
**P1dB vs.  $P_{IN}$  and Frequency**



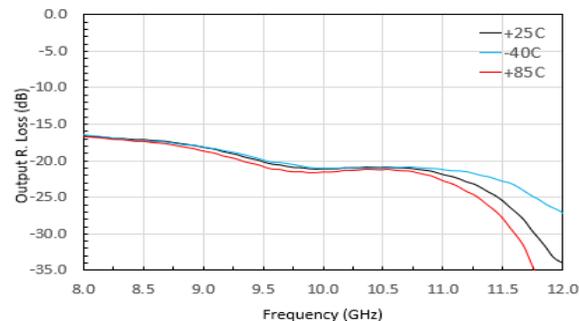
**Input Return Loss vs. Temp**



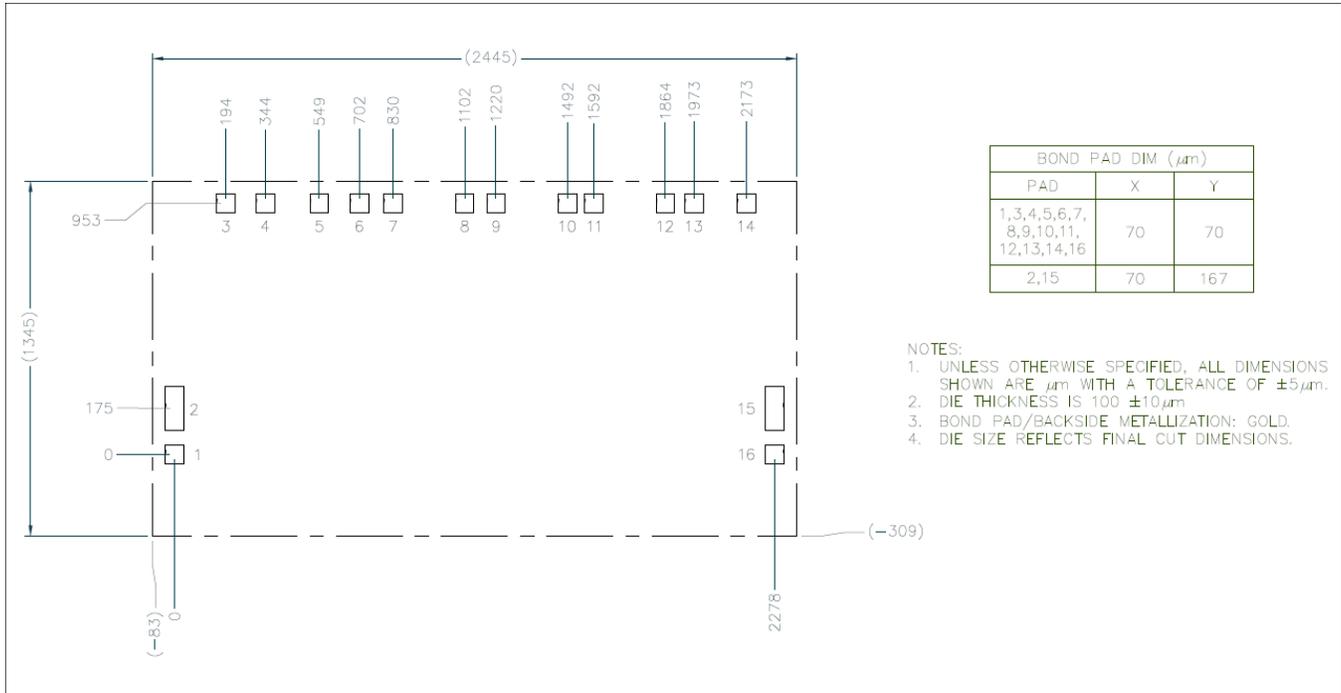
**$I_{IP3}$  vs. BITs and Frequency**



**Output Return Loss vs. Temp**



**Die Outline**



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